



uniformly varied from  $\rho_{A_0} = D_B/2$  to  $\rho_{A_N} = D_M/2$ , such that  $\Delta\rho_A = \rho_{A_n} - \rho_{A_{n-1}} = (D_M/2)/N$ . The position of  $T_n$  is located by:

$$z_{T_n} \hat{z} + \rho_{T_n} \hat{\rho}, \quad (1)$$

where  $\rho_{T_n}$  and  $z_{T_n}$  are the coordinates of  $T_n$ .  $\rho_{T_n}$  is the midpoint between  $\rho_{A_{n-1}}$  and  $\rho_{A_n}$ . In this work, we considered  $z_{T_n} = z_A$ , which causes an aperture-field with uniform phase and a prescribed amplitude distribution. It is emphasized that  $T_n$  can be arbitrarily localted (see Fig. 1), allowing phase control. Under GO properties, the energy contained in the ray beam (between  $\theta_{F_{n-1}}$  and  $\theta_{F_n}$ ), incident on the conic section  $S_n$  is conserved immediately after the second reflection by the  $n$ -th ellipse (see Fig. 2). In the integral form, the conservation of energy is expressed as:

$$\int_{\theta_{F_{n-1}}}^{\theta_{F_n}} G_F(\theta_F) r_F^2 \sin \theta_F d\theta_F = L_F \int_{\rho_{A_{n-1}}}^{\rho_{A_n}} G_A(\rho) \rho d\rho, \quad (2)$$

where  $G_F(\theta_F)$  is the radiated feed power density,  $G_A(\rho)$  is the desired aperture (focal plane) power density and  $L_F$  is a normalization factor given by:

$$L_F = \int_0^{\theta_E} G_F(\theta_F) r_F^2 \sin \theta_F d\theta_F / \int_{D_B/2}^{D_M/2} G_A(\rho) \rho d\rho. \quad (3)$$

From (2) we get  $\theta_{F_n}$  (feed ray direction) by an iterative process starting at  $n = 0$  and  $\theta_{F_0} = 0$  and finishing when  $n = N$  for  $\theta_{F_N} = \theta_E$ , where  $\theta_E$  is the edge angle of the subreflector.

In order to obtain each pair of  $S_n$  and  $M_n$ , for  $n = 1, \dots, N$ , it is necessary to determine only three parameters of  $S_n$ : the interfocal distance ( $2c_n$ ), eccentricity ( $e_n$ ) and the tilt angle ( $\beta_n$ ). Thus, three equations are required. The parameters of  $M_n$ , interfocal distance ( $2C_n$ ), eccentricity ( $\epsilon_n$ ) and the tilt angle ( $\gamma_n$ ), are further calculated from  $2c_n$ ,  $e_n$  and  $\beta_n$ .

The first equation of the shaping process is obtained from the polar equation of  $S_n$ :

$$r_{F_{n-1}} = \frac{a_n}{b_n \cos \theta_{F_{n-1}} + d_n \sin \theta_{F_{n-1}} - 1}, \quad (4)$$

where

$$a_n = c_n(e_n - 1/e_n), \quad (5)$$

$$b_n = e_n \cos \beta_n, \quad (6)$$

$$d_n = e_n \sin \beta_n. \quad (7)$$

Subscript  $n-1$  in (4) indicates that the respective values of  $r_F$  and  $\theta_F$  are given from the previous iteration. The iterative process starts at  $n = 0$  and  $r_{F_0} = V_S$ , where is the distance between the origin  $O$  and the subreflector apex, as shown in Fig. 1.

Considering the ellipse  $M_n$ , one obtains the following relation:

$$r_M(\theta_M) = \frac{A_n(\eta_M^2 + 1)}{B_n(\eta_M^2 - 1) + 2\eta_M D_n - (\eta_M^2 + 1)} \quad (8)$$

for  $\theta_{M_{n-1}} \leq \theta_M \leq \theta_{M_n}$ , where:

$$A_n = C_n(\epsilon_n - 1/\epsilon_n), \quad (9)$$

$$B_n = \epsilon_n \cos \gamma_n, \quad (10)$$

$$D_n = \epsilon_n \sin \gamma_n. \quad (11)$$

$$\eta_M = \cot\left(\frac{\theta_M}{2}\right) = \left[ \frac{b_n - d_n \eta_F + 1}{d_n + \eta_F(b_n - 1)} \right], \quad (12)$$

where  $\eta_F = \cot(\theta_F/2)$ . In (12), it is expressed the relation between the incidence ( $\theta_F$ ) and reflection ( $\theta_M$ ) directions for the conic section  $S_n$  (see Fig. 2).

From the polar equations of  $S_n$  and  $M_n$  one can show that the length of the optical path ( $\ell_n$ ) from the feed phase-center to the focus  $T_n$  with  $z_{T_n} = z_A$ :

$$\ell_n = \frac{2c_n}{e_n} + \frac{2C_n}{\epsilon_n}. \quad (13)$$

Interfocal distance ( $2C_n = \overline{T_n P_n}$ ) of (13) is obtained with aid of the Fig. 1, while  $\ell_n$  and  $z_{T_n}$  must be specified a priori. The remaining two equations are determined by mapping the ray-direction ( $\theta_F \rightarrow \theta_T$ ) from the feed phase-center to the focus  $T_n$ . Consequently, it can be shown that the relation between the  $\rho$ -coordinates of the main-reflector and  $T_n$  to iterations ( $n-1$ ) and ( $n$ ) are given by:

$$r_{M_{n-1}}(\sin \theta_{M_{n-1}} - \sin \theta_{T_{n-1}}) + \frac{2C_n}{\epsilon_n} \sin \theta_{T_{n-1}} + \rho_{P_n} = \rho_{T_n}, \quad (14)$$

$$r_{M_n}(\sin \theta_{M_n} - \sin \theta_{T_n}) + \frac{2C_n}{\epsilon_n} \sin \theta_{T_n} + \rho_{P_n} = \rho_{T_n}, \quad (15)$$

where  $\rho_{P_n}$  is the  $\rho$ -coordinate of  $P_n$  and for  $\theta_{M_{n-1}} \leq \theta_M \leq \theta_{M_n}$  and  $\theta_{T_{n-1}} \leq \theta_T \leq \theta_{T_n}$ :

$$\sin \theta_M = \frac{2\eta_M}{\eta_M^2 + 1}; \quad \sin \theta_T = \frac{2\eta_T}{\eta_T^2 + 1}, \quad (16)$$

with  $\eta_M$  given by (11) and

$$\eta_T = \cot\left(\frac{\theta_T}{2}\right) = \left[ \frac{g_1 - g_3 + \eta_F(1 + g_2 - g_4)}{1 - g_2 + \eta_F(g_1 + g_3) - g_4} \right], \quad (17)$$

where:

$$g_1 = D_n - d_n; \quad (18)$$

$$g_2 = B_n - b_n; \quad (19)$$

$$g_3 = d_n B_n - b_n D_n; \quad (20)$$

$$g_4 = b_n B_n + d_n D_n. \quad (21)$$

Note that  $\gamma_n$  is determined by Fig. 2. System (4), (14) and (15) must be solved numerically in order to obtain  $2c_n$ ,  $e_n$  and  $\beta_n$ . With these parameters,  $2C_n$  (Fig. 2) is readily determined and  $\epsilon_n$  calculated from (13). The subreflector is given by the vector:

$$r_{F_n}(\cos \theta_{F_n} \hat{z} + \sin \theta_{F_n} \hat{\rho}). \quad (22)$$

with  $r_{F_n}$  given by (4) substituting ( $n-1$ ) by ( $n$ ). The main-reflector is located by the following vector:

$$(r_{M_n} \cos \theta_{M_n} + 2c_n \cos \beta_n) \hat{z} + (r_{M_n} \sin \theta_{M_n} + 2c_n \sin \beta_n) \hat{\rho}, \quad (23)$$

where:

$$\cos \theta_M = \frac{\eta_M^2 - 1}{\eta_M^2 + 1}. \quad (24)$$

The iterations are repeated until  $\theta_{F_N} = \theta_E$  for  $n = N$  [1]. The formulation introduced is derived for ADC-like antenna, but can be easily extended to three other axis-symmetric dual-reflector configurations: axis-displaced Gregorian (ADG), ellipse and hyperbola (ADH) [1].

### III. RESULTS

The synthesis process started from a classical configuration, designed with  $D_M = 100\lambda$ ,  $D_B = D_S = 10\lambda$ ,  $\theta_E = 30^\circ$ , and  $\ell_0 = 50\lambda$  (constant path length at  $z_A = 0$ ) [1]. The operating frequency is 5 GHz, such that  $D_M = 6\text{m}$ . In order to evaluate the shaping procedure proposed in Section II, an ADC-like configuration is shaped with a uniform illumination distribution [ $\ell_n = \ell_0$  and  $G_A(\rho) = \text{cte.}$ ] over the aperture ( $D_B/2 \leq \rho_{A_n} \leq D_M/2$ ), to increase the gain of the antenna. The adopted feed model, with  $p = 83$ , is [1]:

$$G_F(\theta_F) = \cos^{2p}(\theta_F/2)/r_F^2. \quad (25)$$

The iterative procedure starts with  $r_{F_0} = V_S = 6.81\lambda$  for  $n = 0$  and  $z_{T_n} = 100\lambda$ . The system of equations (4), (14) and (15) was numerically solved numerically to obtain  $2c_n$ ,  $e_n$  and  $\beta_n$ . Consequently,  $2C_n$ ,  $\epsilon_n$  and  $\gamma_n$  were further determined.

Figure 3 shows the classical and shaped reflector's generatrices, where one can observe the main differences between the geometries. The radiation characteristics obtained by the method-of-moments (MoM) in plane  $\phi = 45^\circ$  are represented in Fig. 4 at 5GHz. The results show good agreement when compared to a case presented in [1] (Fig. 4). As expected, the gain of the shaped arrangement (49.2dBi) is higher than the classical configuration (47.6dBi), with an increase of the cross-polarization of the shaped antenna, according to Fig. 4. To investigate the numerical convergence of this new technique, in Fig. 5 is presented the error (RMS) as a function of the steps-number ( $N$ ). As a reference, we use a shaped antenna with a large number of points ( $\approx 80000$ ) for the sub- and main-reflectors. The RMS errors were obtained from the  $r_{F_n}$  distances and  $z_{M_n}$  coordinates, respectively. From Fig. 5, it can be seen that the RMS error decreases when  $N$  increases, as expected.

### IV. CONCLUSIONS

A new formulation for the GO shaping of the axis-symmetric dual-reflector antennas to control amplitude and phase of the aperture-field was presented. The procedure was easily formulated using the conic representation in polar coordinates. An ADC antenna was successfully shaped to obtain uniform aperture distribution [1]. The electromagnetic performance of the designed antenna was achieved with accurate analysis provided by the MoM technique.

### ACKNOWLEDGMENT

This work has been supported by the Brazilian agencies CAPES, CAPES/PROCAD 068419/14, CNPq and FAPEMIG.

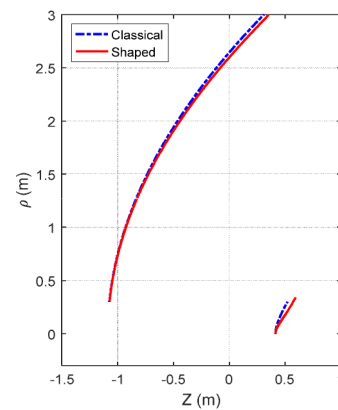


Fig. 3. Classical and shaped ADC-like configurations.

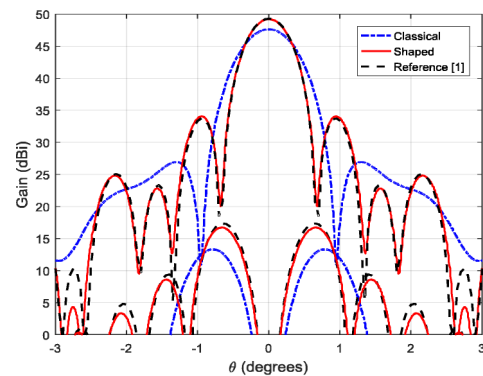


Fig. 4. MoM radiation pattern for  $\phi = 45^\circ$ .

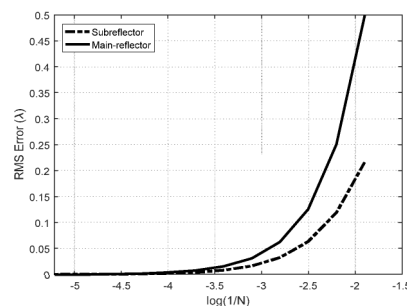


Fig. 5. RMS errors of the shaped ADC reflectors as function of  $N$ .

### REFERENCES

- [1] F. J. S. Moreira and J. R. Bergmann, "Shaping axis-symmetric dual-reflector antennas by combining conic sections," *IEEE Trans. Antennas Propagat.*, vol. 59, no. 3, pp. 1042–1046, March, 2011.
- [2] V. Galindo, "Design of dual-reflector antennas with arbitrary phase and amplitude distributions," *IEEE Trans. Antennas Propagat.*, vol. AP-12, no. 4, pp. 403–408, Jul. 1964.
- [3] F. J. S. Moreira, A. Prata, Jr. and J. R. Bergmann, "GO shaping of omnidirectional dual-reflector antennas for a prescribed equi-phase aperture field distribution," *IEEE Trans. Antennas Propagat.*, vol. 55, no. 1, pp. 99–106, Jan. 2007.